# BRS397W361ACA

3-phase stepper motor - 2.26Nm - shaft Ø 12mm - L=68 mm - w/o brake - conn





#### Main

Range compatibility	Lexium SD3
Product or component type	Motion control motor
Device short name	BRS3
Maximum mechanical speed	3000 rpm
Motor type	3-phase stepper motor
Number of motor poles	6
Supply voltage limits	230 V AC 325 V DC
Mounting support	Flange
Motor flange size	85 mm
Length	111 mm
Centring collar diameter	60 mm

#### Complementary

Complementary		
Centring collar depth	2 mm	
Number of mounting holes	4	
Mounting holes diameter	6.5 mm	
Circle diameter of the mounting holes	98.99 mm	
Electrical connection	Connector	
Feedback type	Single turn encoder	
Speed feedback resolution	10000 points/turn	
Holding brake	Without	
Shaft end	Untapped	
Second shaft	Without second shaft end	
Shaft diameter	12 mm	
Shaft length	30 mm	
Nominal torque	2 N.m	
Peak stall torque	1.9 N.m	
Continuous stall torque	1.9 N.m	
Holding torque	2.26 N.m	
Rotor inertia	1.1 kg.cm²	
Resolution	1000 points/turn 1.8°, 0.9°, 0.72°, 0.36°, 0.18°, 0.09°, 0.072°, 0.036° step angle 200, 400, 500, 1000, 2000, 4000, 5000, 10000 steps number of full steps per revolution	
Accuracy error	+/- 6 arc min	
Maximum starting frequency	5.3 kHz	
[ln] rated current	1.75 A	
Resistance	6.5 Ohm (winding)	
Time constant	7 ms	
Maximum radial force Fr	100 N (first shaft end) 50 N (second shaft end)	
Maximum axial force Fa	175 N (tensile force) 30 N (force pressure)	
Service life in hours	20000 h (bearing)	
Angular acceleration	200000 rad/s²	
Net weight	2.1 kg	

## Environment

Standards	IEC 60072-1 EN 50347	
Type of cooling	Natural convection	
Ambient air temperature for operation	-2540 °C	
Ambient air temperature for storage	-2570 °C	
Operating altitude	<= 1000 m without power derating	
Relative humidity	1585 % without condensation	
Vibration resistance	20 m/s² maximum A conforming to EN/IEC 60034-14	
IP degree of protection	IP41 shaft bushing: conforming to EN/IEC 60034-5 IP56 total except shaft bushing: conforming to EN/IEC 60034-5	
Temperature class	F winding conforming to IEC/EN 60034-1	

# Packing Units

Unit Type of Package 1	PCE
Number of Units in Package 1	1
Package 1 Height	22.5 cm
Package 1 Width	19 cm
Package 1 Length	40 cm
Package 1 Weight	2.734 kg
Unit Type of Package 2	S06
Number of Units in Package 2	12
Package 2 Height	73.5 cm
Package 2 Width	60 cm
Package 2 Length	80 cm
Package 2 Weight	45.808 kg
Unit Type of Package 3	P06
Number of Units in Package 3	12
Package 3 Height	77 cm
Package 3 Width	80 cm
Package 3 Length	60 cm
Package 3 Weight	41.308 kg

## Offer Sustainability

Sustainable offer status	Green Premium product	
REACh Regulation	☑ REACh Declaration	
EU RoHS Directive	Pro-active compliance (Product out of EU RoHS legal scope)	
Mercury free	Yes	
China RoHS Regulation	☑ China RoHS Declaration	
RoHS exemption information	€Yes	
Environmental Disclosure	Product Environmental Profile	
WEEE	The product must be disposed on European Union markets following specific waste collection and never end up in rubbish bins	
PVC free	Yes	

## Contractual warranty

Contraction Warranty		
Warranty	18 months	

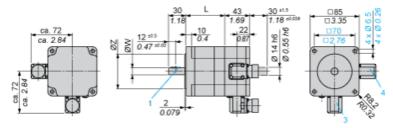
# Product data sheet Dimensions Drawings

# **BRS397W361ACA**

#### **Dimensions**

## 3-Phase Stepper Motor in Connector Version

mm in



3: Motor connection 6 poles

4: Motor connection (optional) 12 poles

Dimensions in mm

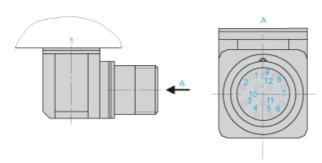
L	Shaft diameter ØW	Centring collar ØZ	Woodruff key DIN 6888 (1)
67.5 (+0.6) (-0.8)	12 h6	60 h8	4 x 6.5

#### Dimensions in in.

L	Shaft diameter ØW	Centring collar ØZ	Woodruff key DIN 6888 (1)
2.66 (+0.023) (-0.031)	0.47 h6	2.36 h8	0.16 x 0.25

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## Wiring Diagram of Encoder Plug on BRS3.



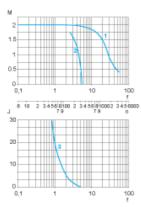
#### 1: Motor housing

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Pin	Designation
1	A
2	A negated
3	В
4	B negated
5	C, I
6	C negated, I negated
7	5 V <sub>GND</sub>
8	+ 5
9	-SENSE
10	+SENSE
11	Temperature sensor
12	Not connected

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## **Torque Characteristics**

Measurement at 1000 Steps/Revolution, Nominal Voltage DC Bus  $U_{N}$  and Phase Current  $I_{N}$ 



M: Torque in Nm
n: Speed in rpm
f: Frequency in kHz
J: Rotor inertia in kg.cm²
1: Pull-out torque
2: Pull-in torque
3: Maximum load inertia